
Spatial-Spectral Cross-Correlation for Change Detection -- A Case Study for Citrus Coverage Change Detection

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OUTLINE

- Background
 - Change Detection Methods
 - Challenge & Solution
 - Spatial-Spectral Cross Correlation
 - Experiment & Results
 - Conclusions
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Background

- Why automatic citrus grove change detection
 - Critical to production inventory monitoring, map updating, and policy making
 - Various changes
 - Tree planted, removed, growing, degenerating
 - Citrus farm conversion and desertion
 - Huge work load
 - Over 700,000 acres in active production
 - Over 1200 maps & photographs analyzed and updated biennially
 - Current manual change detection
 - labor intensive, inefficient, non-ergonomic
 - Automation required
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Background

- How to automate the citrus grove change detection
 - Open problem
 - Many change detection methods existing
 - Are they applicable?
 - Can they meet our requirements?
 - Developing a new method?
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Challenge

- Florida citrus data conditions
 - Different sensors (digital/film)
 - Radiometric differences
 - Dynamic range differences (8-bit and 16-bit)
 - Resolution differences (1m and 2m) =>mixed-pixel
 - Spectral coverage differences (R/G/IR and R/G/B)
 - Unknown data acquiring conditions
 - Sun-angle
 - Atmospheric effects/weather condition
 - Season/date/time
 - Unknown sensor parameters and no calibration
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Original Images

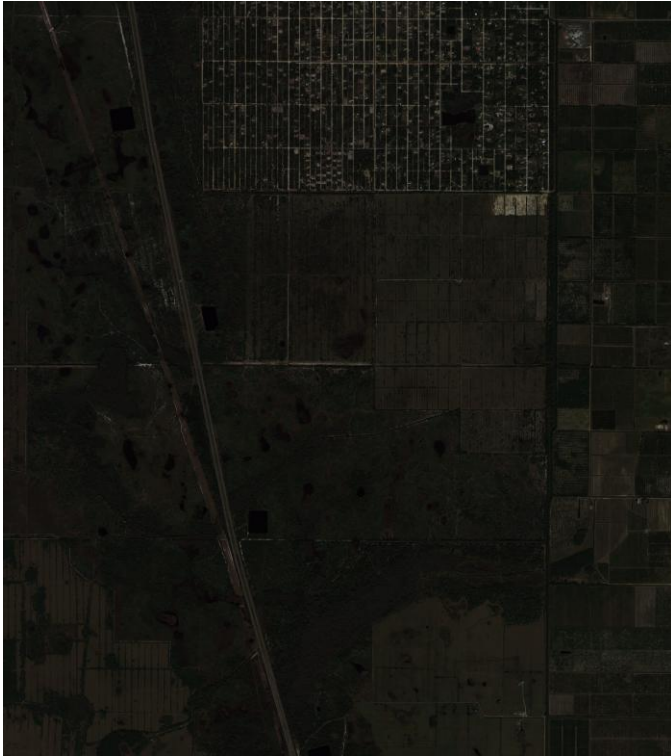


Figure 1. Original 2004 16-bit image

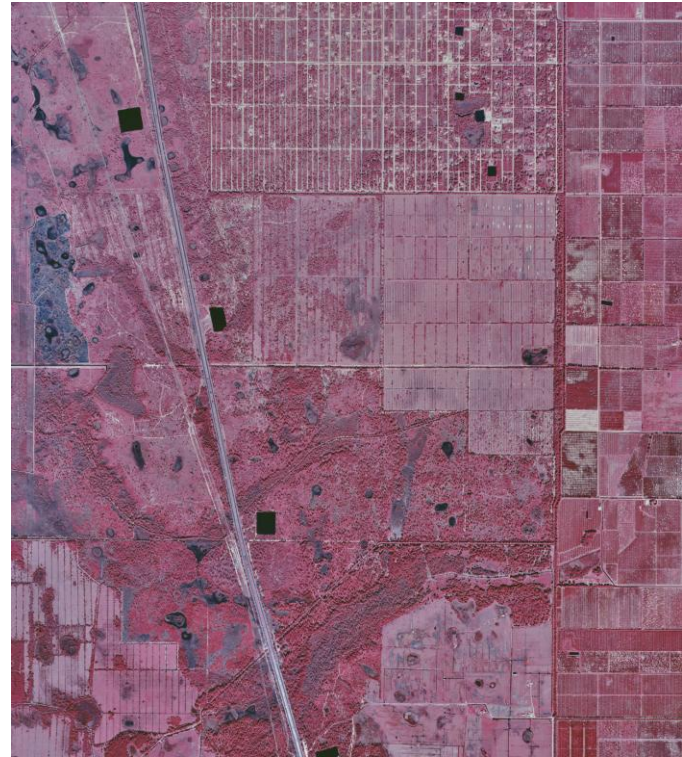
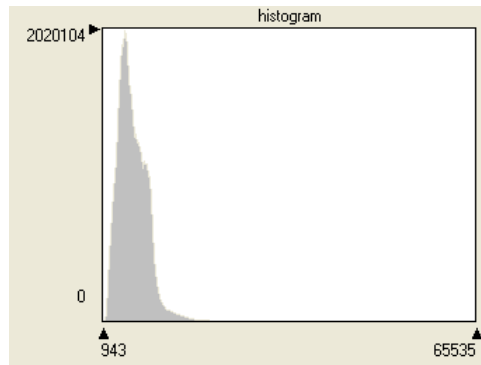
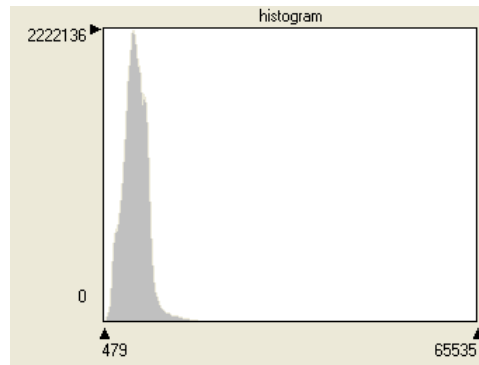


Figure 2. Original 1999 8-bit image

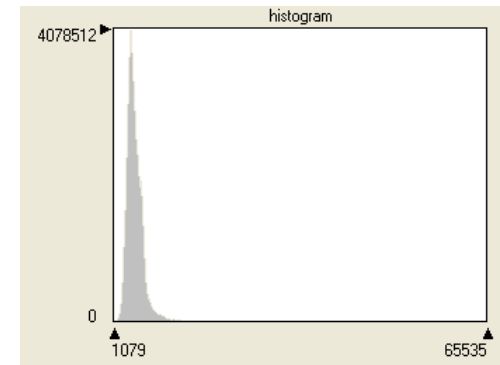
Histogram of Original Images



a) band-1 Histogram

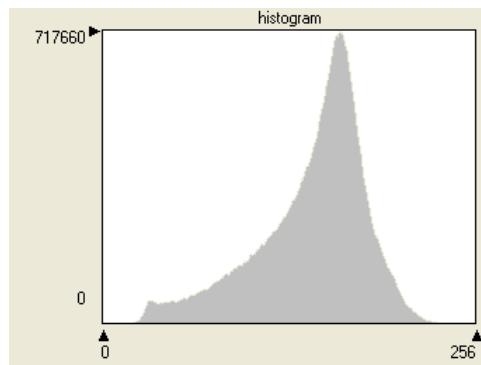


b) band-2 Histogram

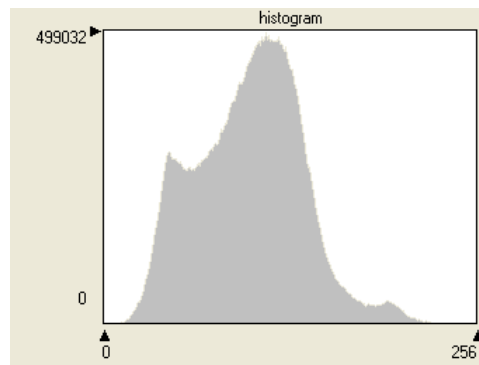


c) band-3 Histogram

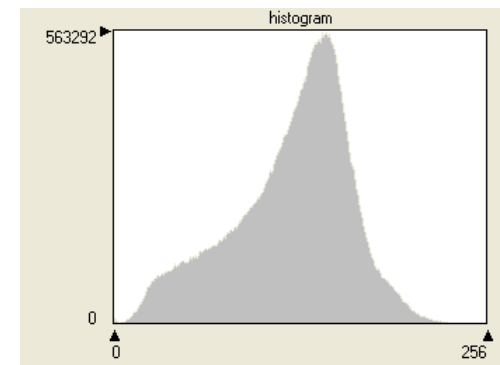
Figure 3. Original 2004 16-bit image histograms



a) band-1 Histogram



b) band-2 Histogram



c) band-3 Histogram

Figure 4. Original 1999 8-bit image histograms

Change Detection Methods (I)

- Pre-classification
 - Various methods:
 - Image differencing (normalized/non-normalized)
 - Change vector analysis
 - Inner product analysis
 - Image ratioing
 - Vegetation index differencing
 - Spectral cross-correlation
 - Principal component analysis (PCA)
 - All are spectral based
 - All are sensitive to misregistration, mixed pixel
 - All are straightforward and easy to implement except PCA
 - Some are sensitive to radiometric distortion (difference)
 - Some are sensitive to dynamic range
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Change Detection Methods

- Post-classification
 - Two steps:
 - Classification
 - Interpreting and Comparing classification results
 - Detection accuracy depends on the classification accuracy
 - Upper bound : Difference of two image classification errors
 - Lower bound : Sum of two classification errors
 - Complicated
 - Experienced & well trained analyst needed
 - Interpretation of classification result needed
 - Extra errors may be introduced
 - Intra-class change is not defined
 - Difficult in detecting citrus growth
 - Suitable for large scale land coverage change detection (many cover types involved)
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What We Expected

- Minimum human-machine interaction
 - Minimum experience and training for operation
 - Minimum preprocessing
 - Easy to understand and easy to implement
 - Robust to different image data conditions
 - Robust to radiometric difference
 - Invariant to dynamic range
 - Robust to the mixed-pixels
 - Robust to the noise
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Solution

- Utilize the spectral correlation
 - Invariant to image dynamic range
 - Robust to Radiometric difference
 - Easy to understand and easy to implement
 - Minimal pre-processing
 - But sensitive to mixed-pixel and to noise
 - How to improve it
 - Develop a novel method by using the spatial information
 - How to use the spatial information
 - Integrate the spatial correlation concept
 - Result -Spatial-Spectral Cross Correlation
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Spectral Cross Correlation

Let $f(x, y, k)$ and $g(x, y, k)$ be two multi-spectral images
Then the spectral cross correlation coefficient is given by:

$$c(i, j) = \frac{[g(i, j) - \bar{g}(i, j)]^T [f(i, j) - \bar{f}(i, j)]}{\sqrt{\|g(i, j) - \bar{g}(i, j)\|^2} \sqrt{\|f(i, j) - \bar{f}(i, j)\|^2}}$$

Where

$$g(i, j) = \begin{bmatrix} g(i, j, 1) \\ g(i, j, 2) \\ \dots \\ g(i, j, L) \end{bmatrix} \quad f(i, j) = \begin{bmatrix} f(i, j, 1) \\ f(i, j, 2) \\ \dots \\ f(i, j, L) \end{bmatrix}$$

- ❑ No spatial information, Spectral signature similarity only
- ❑ Sensitive to mixed-pixels and noise.

Spatial Cross Correlation

Let $f(x, y)$ and $g(x, y)$ be two single band images

Then the spectral cross correlation coefficient is given by:

$$c(i, j) = \frac{\sum_{x \in W} \sum_{y \in W} [g(i+x, j+y) - \bar{g}(i, j)][f(i+x, j+y) - \bar{f}(i, j)]}{\sqrt{\sum_{x \in W} \sum_{y \in W} [g(i+x, j+y) - \bar{g}(i, j)]^2} \sqrt{\sum_{x \in W} \sum_{y \in W} [f(i+x, j+y) - \bar{f}(i, j)]^2}}$$

Where

$$\bar{g}(i, j) = \frac{1}{W^2} \sum_{x \in W} \sum_{y \in W} g(i+x, j+y), \quad \bar{f}(i, j) = \frac{1}{W^2} \sum_{x \in W} \sum_{y \in W} f(i+x, j+y)$$

- ❑ Single band, no spectral signature, spatial similarity only
- ❑ Not proper for change detection

Normalized Spatial-Spectral Cross Correlation (SSC)

Let $f(x, y, k)$ and $g(x, y, k)$ be two multi-spectral images

Then the spectral cross correlation coefficient is given by:

$$c(i, j) = \frac{\sum_{x \in W} \sum_{y \in W} [g(i+x, j+y) - \bar{g}(i, j)]^T [f(i+x, j+y) - \bar{f}(i, j)]}{\sqrt{\sum_{x \in W} \sum_{y \in W} \|g(i+x, j+y) - \bar{g}(i, j)\|^2} \sqrt{\sum_{x \in W} \sum_{y \in W} \|f(i+x, j+y) - \bar{f}(i, j)\|^2}}$$

Where

$$\bar{g}(i, j) = \frac{1}{W^2 L} \sum_{x \in W} \sum_{y \in W} \sum_{k=1}^L g(i+x, j+y, k), \quad \bar{f}(i, j) = \frac{1}{W^2 L} \sum_{x \in W} \sum_{y \in W} \sum_{k=1}^L f(i+x, j+y, k)$$

□ Multi-spectral signature and local spatial similarity

Experiments & Results

- Implementation & preprocessing
 - 2 meter 1999 Image re-sampled into 1 m
 - Images were pre-registered individually
 - Correlation computed over overlapping area
 - Change maps thresholded by ISODATA algorithm
 - Results
 - Comparing correlation maps of SC and SSC
 - Comparing change maps between SC and SSC
 - Zooming the correlation maps
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Enhanced Original Images



Figure 5. Enhanced 2004 16-bit image



Figure 6. Enhanced 1999 8-bit image

Correlation Maps

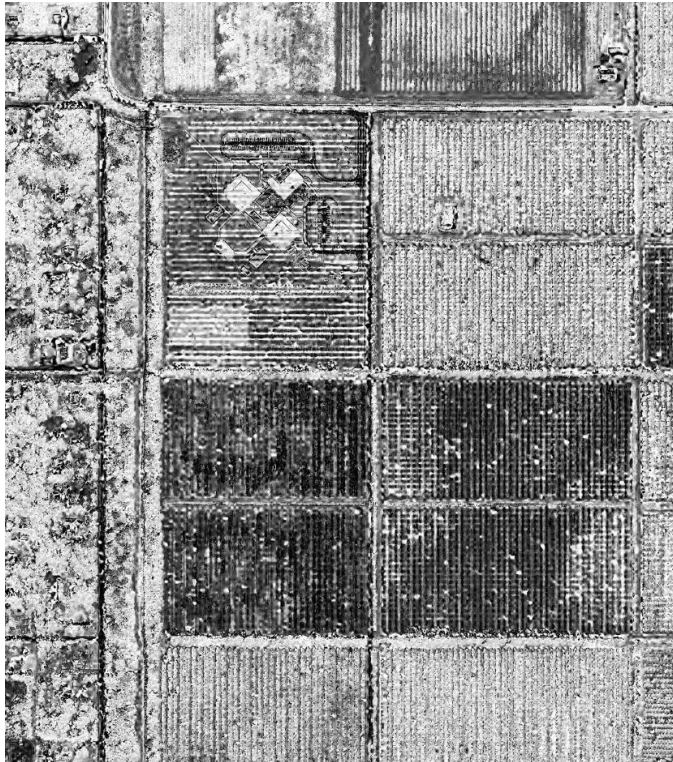
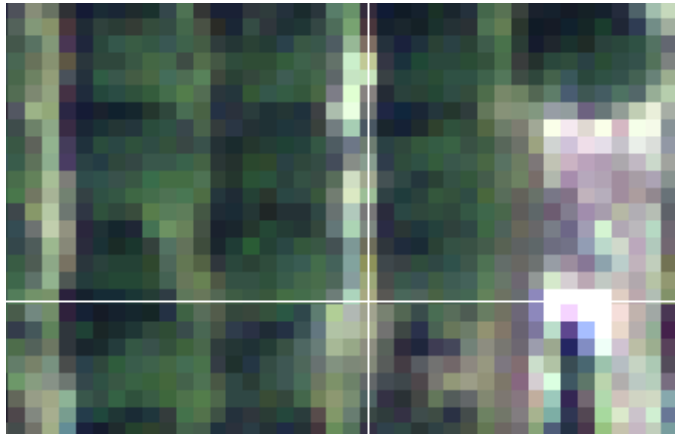


Figure 7. Spectral Correlation Map (SC)
W=1

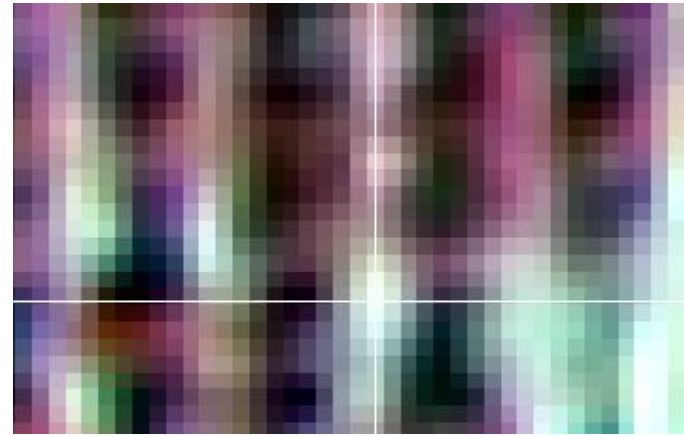


Figure 8. Spatial-Spectral Correlation Map
W=3

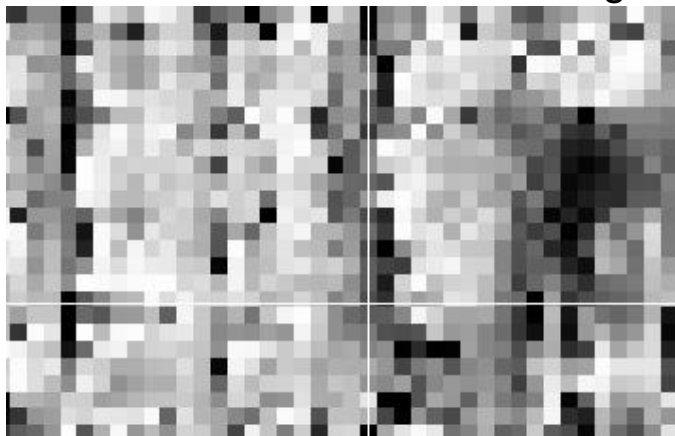
Zoomed Correlation Maps



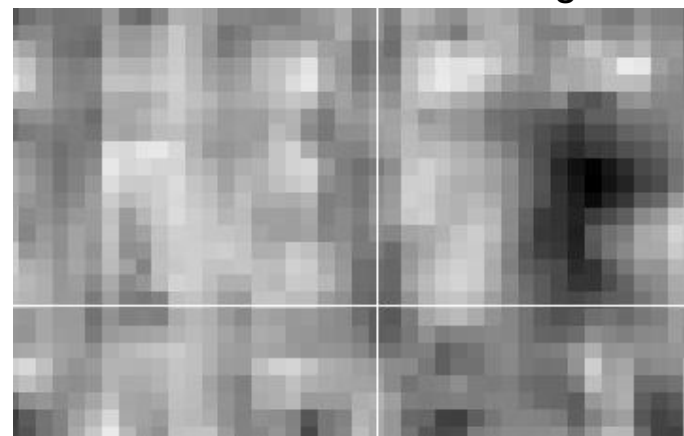
a. Enhanced 2004 16-bit image



b. Enhanced 1999 8-bit image



c. Zoomed in SC Map



d. Zoomed in SSC Map with $W=3$

Figure 11. Pixel view

Change Maps

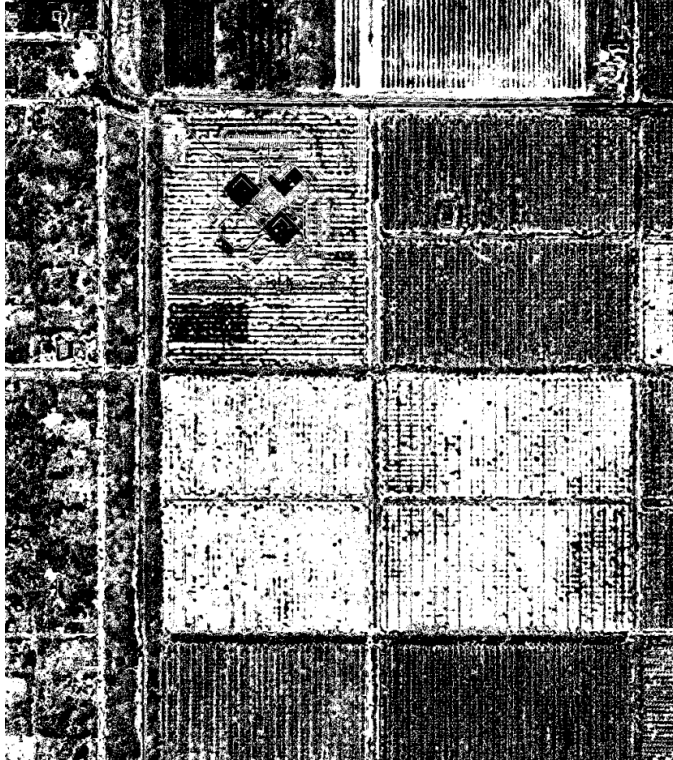


Figure 9. Threshold Change Map from SC Map $W = 1$



Figure 10. Threshold Change Map from SSC Map with $W = 3$

Conclusions

- Presented a new concept of spatial-spectral cross correlation
 - Generalized the spatial correlation and the spectral correlation method into a spatial-spectral domain;
 - Proved both spatial correlation and spectral correlation are special cases of the Spatial-Spectral correlation.
 - Spatial-spectral cross correlation method
 - Spatial and spectral information
 - Minimal pre-processing (only re-sampling)
 - Robust to radiometric differences
 - Invariant to image dynamical range differences
 - Robust to noise as evidenced by less salt & pepper effect
 - Robust to the mixed-pixel effect
 - Less sensitive to misregistration.
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Conclusions

- More attractive for multi-temporal image change detection with different spatial resolutions because of the robustness to the mixed-pixel effect
 - Shortcomings:
 - Relatively computational intensive
 - Not suitable for saturated image (with the small variance)
 - Overall, this method can be used for generating a correlation map as a global navigation tool or as a local change indication for images of different spatial resolutions
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Thank You!

Question?